

Freeform Search

Database:

US Pre-Grant Publication Full-Text Database
 US Patents Full-Text Database
 US OCR Full-Text Database
 EPO Abstracts Database
 JPO Abstracts Database
 Derwent World Patents Index
 IBM Technical Disclosure Bulletins

Term:

l17 and L18

Display: Documents in Display Format: Starting with Number Generate: ☐ Hit List ☒ Hit Count ☐ Side by Side ☐ Image

Search

Clear

Interrupt

Search History

DATE: Friday, October 13, 2006 [Purge Queries](#) [Printable Copy](#) [Create Case](#)

Set Name Query
 side by side

Hit Count Set Name
 result set

DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=OR

<u>L19</u>	l17 and L18	34	<u>L19</u>
<u>L18</u>	grip or (coefficient adj friction)	593972	<u>L18</u>
<u>L17</u>	l5 and L16	89	<u>L17</u>
<u>L16</u>	vehicle	2129867	<u>L16</u>
<u>L15</u>	vehicle	2129867	<u>L15</u>
<u>L14</u>	(load adj value) and (original adj value)	254	<u>L14</u>
<u>L13</u>	l3 and L12	1	<u>L13</u>
<u>L12</u>	contact adj load adj value	15	<u>L12</u>
<u>L11</u>	l5 and L10	0	<u>L11</u>
<u>L10</u>	ground adj sensor	1122	<u>L10</u>
<u>L9</u>	l5 and L8	1	<u>L9</u>
<u>L8</u>	ground same (load adj sensor)	283	<u>L8</u>
<u>L7</u>	ground near (load adj sensor)	18	<u>L7</u>
<u>L6</u>	ground near4 (load adj sensor)	46	<u>L6</u>
<u>L5</u>	l3 and L4	89	<u>L5</u>
<u>L4</u>	wheel adj sensor	5210	<u>L4</u>
<u>L3</u>	l1 and L2	886	<u>L3</u>
<u>L2</u>	vehicle adj control\$	55599	<u>L2</u>
<u>L1</u>	plurality adj sensor	27167	<u>L1</u>

END OF SEARCH HISTORY

Refine Search

Search Results -

Terms	Documents
L17 and L25	0

Database:

US Pre-Grant Publication Full-Text Database
 US Patents Full-Text Database
 US OCR Full-Text Database
 EPO Abstracts Database
 JPO Abstracts Database
 Derwent World Patents Index
 IBM Technical Disclosure Bulletins

Search:

L26

Refine Search

Recall Text

Clear

Interrupt

Search History

DATE: Friday, October 13, 2006 [Purge Queries](#) [Printable Copy](#) [Create Case](#)

<u>Set Name</u> side by side	<u>Query</u>	<u>Hit Count</u>	<u>Set Name</u> result set
	<i>DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=OR</i>		
<u>L26</u>	117 and L25	0	<u>L26</u>
<u>L25</u>	120 or 124	96	<u>L25</u>
	<i>DB=USPT; PLUR=YES; OP=OR</i>		
<u>L24</u>	(4106821 4409664 4430703 3752536 4420814 3503653 4499543 4113321 4643485 4657313 4267575 3930688 4497026 4136912 4494801 4392202 3880474 4408290 4315213 4384330 2914359 4569560 3637264 4430714 4643492 4435768 4287505 3943345 4270176 4515412 4345796 4335431 3398995 4439832 3985396 4398260 4363523 3938612)! [PN]	38	<u>L24</u>
<u>L23</u>	("4736994" "4718013" "4674049" "4701854") [PN]	4	<u>L23</u>
<u>L22</u>	(4106821 4409664 4430703 3752536 4420814 3503653 4499543 4113321 4643485 4657313 4267575 3930688 4497026 4136912 4494801 4392202 3880474 4408290 4315213 4384330 2914359 4569560 3637264 4430714 4643492 4435768 4287505 3943345 4270176 4515412 4345796 4335431 3398995 4439832 3985396 4398260 4363523 3938612)! [PN]	38	<u>L22</u>
<u>L21</u>	("4736994" "4718013" "4674049" "4701854") [PN]	4	<u>L21</u>
<u>L20</u>	("4718013" "4674049" "4701854") [URPN]	58	<u>L20</u>
	<i>DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=OR</i>		

<u>L19</u>	l17 and L18	34	<u>L19</u>
<u>L18</u>	grip or (coefficient adj friction)	593972	<u>L18</u>
<u>L17</u>	l5 and L16	89	<u>L17</u>
<u>L16</u>	vehicle	2129867	<u>L16</u>
<u>L15</u>	vehicle	2129867	<u>L15</u>
<u>L14</u>	(load adj value) and (original adj value)	254	<u>L14</u>
<u>L13</u>	l3 and L12	1	<u>L13</u>
<u>L12</u>	contact adj load adj value	15	<u>L12</u>
<u>L11</u>	l5 and L10	0	<u>L11</u>
<u>L10</u>	ground adj sensor	1122	<u>L10</u>
<u>L9</u>	l5 and L8	1	<u>L9</u>
<u>L8</u>	ground same (load adj sensor)	283	<u>L8</u>
<u>L7</u>	ground near (load adj sensor)	18	<u>L7</u>
<u>L6</u>	ground near4 (load adj sensor)	46	<u>L6</u>
<u>L5</u>	l3 and L4	89	<u>L5</u>
<u>L4</u>	wheel adj sensor	5210	<u>L4</u>
<u>L3</u>	l1 and L2	886	<u>L3</u>
<u>L2</u>	vehicle adj control\$	55599	<u>L2</u>
<u>L1</u>	plurality adj sensor	27167	<u>L1</u>

END OF SEARCH HISTORY